

Recent results of ECRH/ECCD experiments on TCV

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Talk outline

- TCV Tokamak overview and features
 - ECH/ECCD system
 - Real-time control
- Recent results of ECH/ECCD experiments
 - Real-time control of
 - Sawtooth period
 - Peak-in-profile
 - Plasmas with internal electron transport barriers (eITBs)
 - Creation and sustainment in steady-state
 - Steady-state 100% bootstrap current
 - Global oscillations, suppression using current density profile perturbations
 - Tearing mode studies
- Conclusions & Summary



TCV Overview

- TCV: Tokamak à Configuration Variable
- R/a = 0.88m/0.25m,
- B_T < 1.45T, I_p < 1.2MA
- High flexibility in plasma shape/position
- 0.9 < elongation < 2.8
- -0.6 < triangularity < 0.9
- t_{pulse} < 4s, T_e < 10keV
- Graphite inner wall

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Flexible ECH/ECCD system

2nd harmonic X2 (82.7GHz)

6 x 0.5MW, 2s gyrotrons

3rd harmonic X3 (118GHz) 3 x 0.5MW, 2s gyrotrons



Real-time control of EC system



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- Digital real-time feedback control of EC system
- EC power/mirror angles can be controlled in Realtime. [Paley, PPCF2007]
- Recently, injection angle was regulated to control
 - Sawtooth period
 - Peak-in-profile



Control of sawtooth period

- Sawtooth crashes periodic core pressure and temperature drop inside q=1 surface.
 - Control is important as sawteeth can trigger NTMs -> confinement loss
- Period can be controlled by localized EC deposition near q=1
 - Causes local changes in the magnetic shear.
 - Sweep of the EC deposition shows a clear peak
 - Hysteresis due to change in *q*=1 surface
 location, caused by global current profile changes.
 - Nonlinear response, system gain changes



Typical signal of central X-rays with sawteeth



Control of sawtooth period

- Linear controller use is limited due to increasing system gain.
- Loop can be either unstable or too slow.
- Solution: nonlinear, gain scheduling controller.
 - Two possible movement speeds depending on requested period.
 - Result: successful tracking of reference signal.



Profile control

- Acquire all 64 DMPX chords, filter, spline fit in real-time
 - Gives soft x-ray emission profile maximum value, peakedness, width, ...
- Objective: control multiple parameters of the profiles using multiple launchers.
- First experiment: control the maximum value (peak) of the line-integrated SXR emission profile by moving one launcher





Peak-in-profile control

- Control the maximum value (peak) of the spline fitted profile
- Reference tracking experiment
 - Subtract measured maximum from given reference
 - Feed error to PI controller
 - Controller adjusts mirror angle



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- Invert line-integrated signals to obtain true profile.
- Control temperature profile instead of SXR emissions
- Use multiple launchers



Scenarios with eITBs

- Electron internal transport barriers created routinely in TCV
 - High pressure gradients in off-axis region
 - confinement improvement 3-6 times
 TCV L-mode scaling
- Created in reversed shear conditions: hollow *j profile, reverse shear q* profile



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- In TCV: steady-state eITB plasmas, lasting several current redistribution times.
 i A phollow current profile
 - Low current and density
 - Non-inductive:
 - Off-axis ECCD.
 - High bootstrap fraction (>50%)

[Sauter, PRL 2005]

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Steady-state 100% bootstrap current

- eITB generates bootstrap current in high pressure gradient region. The bootstrap current profile must then itself generate the barrier.
 - Need for high-pressure gradient region and bootstrap current profile to be *precisely* and *stably* aligned.
- Experimental results
 - Heating during I_{p} ramp-up
 - Only EC Heating (perp. to B field)

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 Quiescent period lasting several current redistribution times (~0.2s)



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Global oscillations during eITB plasmas

- Global oscillations of several plasma quantities (n, I_p, ...) have been observed on several Tokamaks [Giruzzi PRL2003, Hanada ICPP2004].
 - These oscillations are present when approaching the ideal limit *infernal* modes [Ozeki, 1993]. Inherent to high-performance eITB scenarios.
 - In TCV, these can be either sinusoidal (triggered by resistive MHD) or crash-like (triggered by ideal MHD). [G. Turri, PPCF2008, V. Udintsev, PPCF2008]



Physical origins of the oscillations

• Nonlinear coupling between barrier, current profile and MHD



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(1)Barrier forms
(2)Mode is destabilized
(3)Barrier degrades
(4)Mode disappears



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Current density perturbations effects on the oscillatory regime

- Make current density profile less hollow ullet
 - Move away from ideal MHD limit
 - Barrier strength reduces but oscillations are suppressed.
- Experiment: reduce off-axis co-ECCD
 - current profile becomes less hollow,
 - oscillations stop
 - barrier remains



Tearing modes during current profile modulation

- Current profile modulation experiments [Cirant NF2006]
 - Experimental set up
 - One set of gyrotrons aimed for off-axis co-current drive
 - Another set of gyrotrons aimed for off-axis counter current drive
 - Switch gyrotron powers repeatedly
 - Tearing modes are regularly destabilized by current profile changes.
 - Classical destabilization: △'>0.
 [Pletzer POP1999]
 - Goals
 - demonstrate precise control of j profile, important for adv. scenarios
 - Aid predictions of NTM stability limits for ITER.
 - This will be studied in detail during the coming campaign



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Summary & Conclusions

- Recent TCV experiments with ECRH/ECCD
 - Real-time control
 - Demonstration of feedback control of sawtooth period by local EC deposition using non-linear controller.
 - Demonstrate of peak-in-profile control by changing EC deposition location.
 - Scenarios with internal electron transport barriers
 - Steady-state sustainment using off-axis ECCD.
 - 100% bootstrap current in steady-state achieved, no external current drive.
 - Global oscillations, inherent to high performance steady-state scenarios
 - Caused by proximity to the infernal mode limit, interplay between barrier and MHD.
 - Stabilization by current profile perturbations rendering profile less hollow.
 - Localized ECCD deposition effects on tearing stability, aiming at precise control of j profile and NTM stability predictions for ITER.







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Reserve slides



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Peak-in-profile control (2)

- Gyrotron power decrease during the shot
- Shot with feedback control recovers maximum by moving deposition off-axis
- Shot with no feedback does not recover.

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Stabilization of the oscillatory regime

- Example 2: Apply co-current ohmic perturbation
 - Negligible increase in injected power
 - The perturbation will be peaked on-axis due to better conductivity.
 - current profile becomes less hollow
 - oscillations stop

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- barrier is maintained



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